| General conditions |
| :---: |
| 3phase SPWM |
| $\mathbf{V}_{\text {GEon }}=15 \mathrm{~V}$ |
| $\mathbf{V}_{\text {GEoff }}=-15 \mathrm{~V}$ |
| $\mathbf{R}_{\text {gon }}=32 \Omega$ |
| $\mathbf{R}_{\text {goff }}=32 \Omega$ |

Figure 1
Typical average static loss as a function of output current
$\mathrm{P}_{\text {loss }}=\mathrm{f}\left(\mathrm{l}_{\text {out }}\right)$

$\begin{array}{ll}\text { At } \\ \mathrm{T}_{\mathrm{j}}= & 149 \quad \text { C }\end{array}$
$\mathrm{Mi}^{*} \cos \varphi$ from -1 to 1 in steps of 0,2

## Figure 3

Typical average switching loss
as a function of output current


At
$\begin{array}{lll}\mathrm{T}_{\mathrm{j}}= & 149 \quad{ }^{\circ} \mathrm{C}\end{array}$
DC link $=600 \quad \mathrm{~V}$
$\mathrm{f}_{\text {sw }}$ from $\quad 2 \mathrm{kHz}$ to 16 kHz in steps of factor 2

Figure 2

Typical average static loss as a function of output current
$P_{\text {loss }}=f($ lout $)$


At

| $T_{j}=$ | $149 \quad{ }^{\circ} \mathrm{C}$ |
| :---: | :---: |

$\mathrm{Mi}^{*} \cos \varphi$ from -1 to 1 in steps of 0,2
Figure 4
Typical average switching loss
as a function of output current $\quad P_{\text {loss }}=f\left(l_{\text {out }}\right)$


[^0]

At

| $T_{j}=$ | 149 | ${ }^{\circ} \mathrm{C}$ |
| :--- | :--- | :--- |
| $D C$ link $=$ | 600 | $V$ |
| $f_{s w}=$ | 4 | kHz |

Th from $\quad 60^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}$ in steps of $5^{\circ} \mathrm{C}$

## Figure 7

Typical available 50 Hz output current as a function of $\mathrm{Mi}^{*} \cos \varphi$ and switching frequency
$\mathrm{I}_{\text {out }}=\mathrm{f}\left(\mathrm{f}_{\text {sw }}, \mathrm{Mi}^{*} \cos \varphi\right)$


| At |  |  |
| :--- | :--- | :--- |
| $T_{j}=$ | 149 | ${ }^{\circ} \mathrm{C}$ |
| $D C$ link $=$ | 600 | V |
| $\mathrm{~T}_{\mathrm{h}}=$ | 80 | ${ }^{\circ} \mathrm{C}$ |



Typical available 50 Hz output current


At
$\mathrm{T}_{\mathrm{j}}=149 \quad$ C
DC link $=600 \quad V$
$\mathrm{Mi}^{*} \cos \varphi=0,8$
Th from $\quad 60^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}$ in steps of $5^{\circ} \mathrm{C}$

## Figure 8

Typical available $\mathbf{0 H z}$ output current as a function


At

| $T_{j}=$ | 149 | $\circ$ |
| :--- | :--- | :---: |
| $D C$ link $=$ | 600 | V |
| $T_{h}$ from | $60^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}$ in steps of $5^{\circ} \mathrm{C}$ |  |
| $\mathrm{Mi}=$ | 0 |  |



| At |  |  |
| :--- | :--- | :---: |
| $T_{j}=$ | 149 | C |
| DC link $=$ | 600 | V |
| $\mathrm{Mi}=$ | 1 |  |
| $\cos \varphi=$ | 0,80 |  |
| $\mathrm{f}_{\text {sw }}$ from | 2 kHz to 16 kHz in steps of factor 2 |  |

## Figure 11

Typical available overload factor as a function of

| motor power and switching frequency | $P_{\text {peak }} / P_{\text {nom }}=f\left(P_{\text {nom }}, f_{\text {sw }}\right)$ |
| :---: | :---: | :---: | :---: | :---: |

At

| $\mathrm{T}_{\mathrm{j}}=$ | 149 | ${ }^{\circ} \mathrm{C}$ |
| :--- | :--- | :--- |
| DC |  |  |

DC link = 600
$\mathrm{Mi}=\quad 1$
$\cos \varphi=\quad 0,8$
$\mathrm{f}_{\mathrm{sw}}$ from $\quad 1 \mathrm{kHz}$ to 16 kHz in steps of factor 2
$\mathrm{T}_{\mathrm{h}}=80 \quad{ }^{\circ} \mathrm{C}$
Motor eff $=0,85$

Figure 10
Inverter
Typical efficiency as a function of output power efficiency $=f\left(\mathrm{P}_{\text {out }}\right)$


At
$\mathrm{T}_{\mathrm{j}}=\quad 149 \quad{ }^{\circ}$
DC link $=600 \quad V$
$\mathrm{Mi}=1$
$\cos \varphi=\quad 0,80$
$\mathrm{f}_{\mathrm{sw}}$ from $\quad 2 \mathrm{kHz}$ to 16 kHz in steps of factor 2


[^0]:    At
    $\mathrm{T}_{\mathrm{j}}=\quad 149 \quad{ }^{\circ}$
    DC link $=600 \quad \mathrm{~V}$
    $\mathrm{f}_{\mathrm{sw}}$ from $\quad 2 \mathrm{kHz}$ to 16 kHz in steps of factor 2

